



# Least Square Reverse Time Migration

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# Conventional RTM

## Main features

- *Based on full-wave wave equation based propagator*
- *Zero-lag cross-correlation between source & receiver-side wavefields*
- *Earth imaging method for complex geological settings*

## Disadvantages

- *Image does not represent reflectivity*
- *Migration artifacts*
- *Image is source wavelet dependent*
- *Image quality depends on survey geometry*
- *Image amplitude dependent on illumination and depth*

# Goal of least square RTM (LS-RTM)

- Suppress migration artifacts
- Compensate unbalanced illumination issue caused by survey geometry and geological structures
- Enhance image resolution
- Improve image lateral continuity

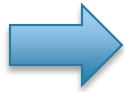
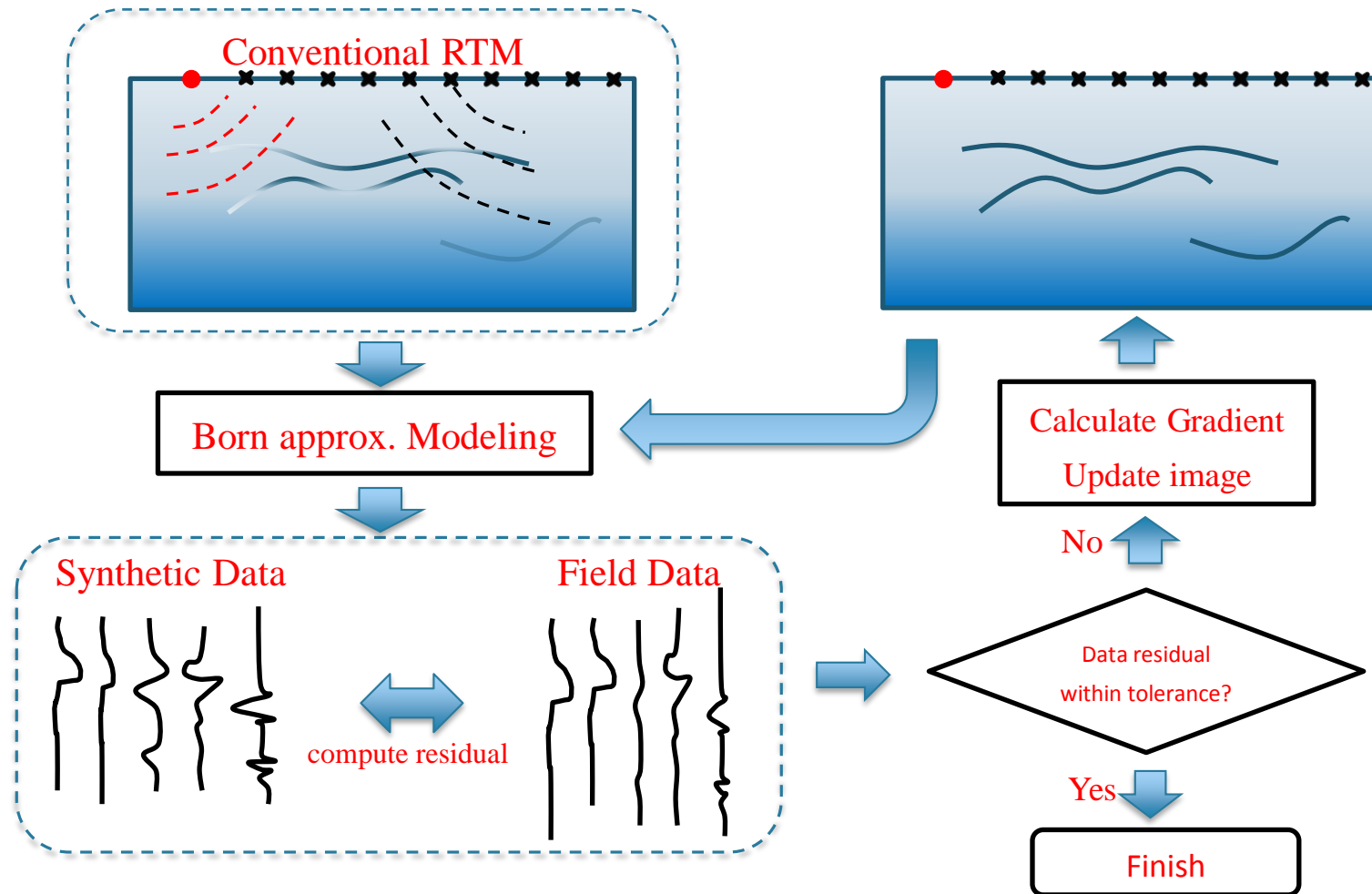


Image = reflectivity

# RTM vs. LS-RTM



RTM – one step procedure

LS-RTM – iterative procedure

# Background velocity & reflectivity

- Two modeling involved in LS-RTM
- Model splits into background velocity model ( $v_g$ ) & reflectivity ( $m$ )
- $v_g$  is for RTM propagator
- $m$  is for scattered data simulation for reflectivity update

$$\nabla^2 p_0 + \omega^2 s_0^2 p_0 = -i\omega\rho Q$$



RTM propagator

$$\nabla^2 \delta p + \omega^2 s_0^2 \delta p \approx -\omega^2 m p_0(\mathbf{r}', \mathbf{r}_s)$$



Scattered data simulation



A linear system

$$d = L(m)$$

$d$  – scattered data

$L$  – linear operator

$m$  – reflectivity

# Optimization in LS-RTM

- Cost function

$$C = \frac{1}{2} \|L(\mathbf{m}) - M\|^2 + \lambda R(\mathbf{m})$$

$M$  – recorded field data

$L$  – linear operator

$\mathbf{m}$  – reflectivity

$\lambda$  – regularization parameter

$R$  – regularization term

$\gamma$  – step-length

$$\begin{aligned} g(\mathbf{m}) &= \nabla_{\mathbf{m}} C \\ &= L^T(\mathbf{m})[L(\mathbf{m}) - M] + \lambda \nabla_{\mathbf{m}} R(\mathbf{m}) \end{aligned}$$

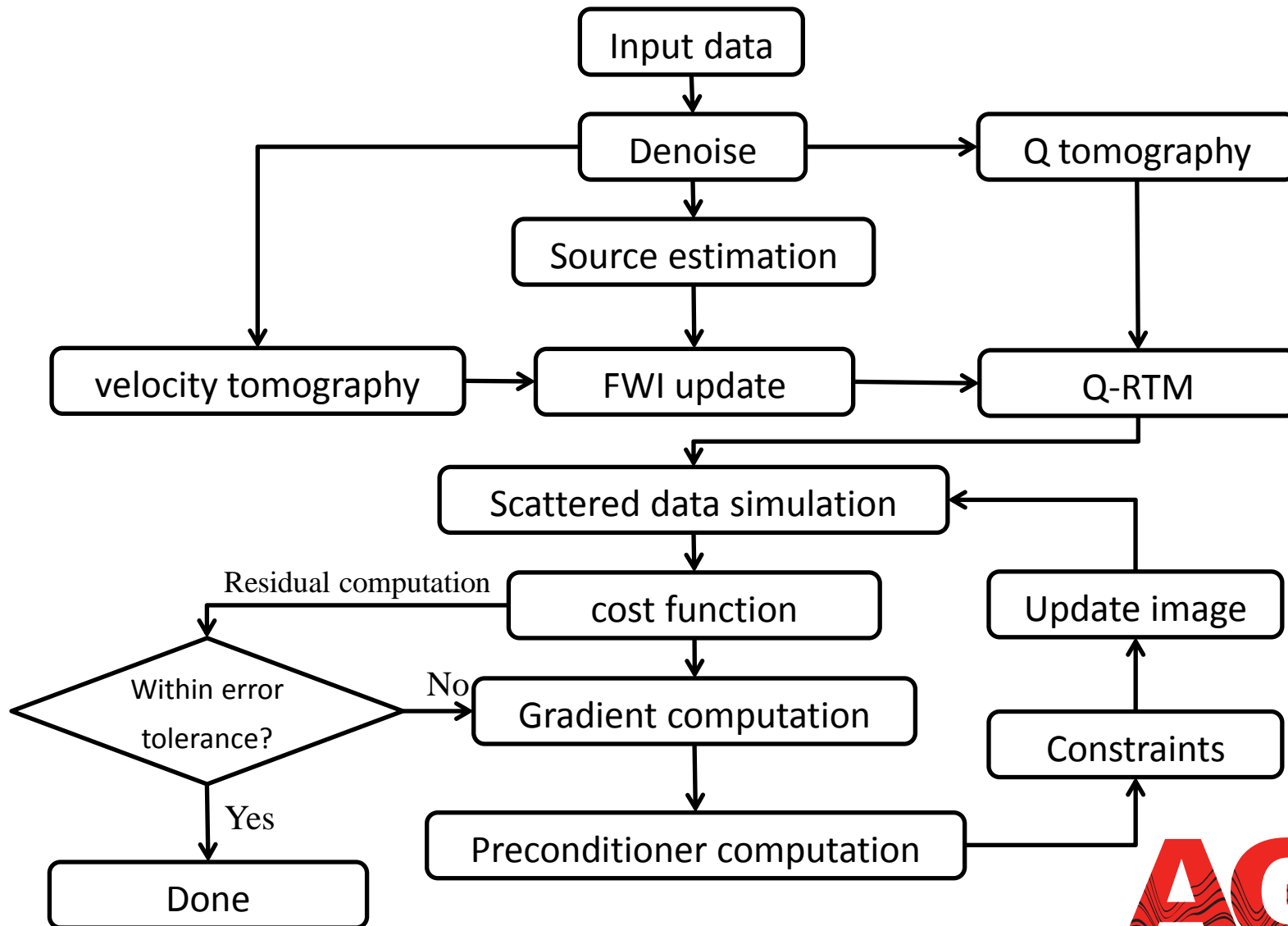


$$\mathbf{m}^{n+1} = \mathbf{m}^n + \gamma \{L^T(\mathbf{m})[L(\mathbf{m}) - M] + \lambda \nabla_{\mathbf{m}} R(\mathbf{m})\}$$

# Challenges in field data LS-RTM

- Wave propagator does not take into account full physics
  - Elastic instead of acoustic
  - Q attenuation
  - Noise
- Source wavelet is unknown
- Velocity model is not accurate
  - Defocusing (especially for shallow region, far-offset)

# AGT's solution to field data LS-RTM





# Unique features of AGT LS-RTM

- Q tomography and Q-RTM are employed to compensate the leakage from Q effect to reflectivity
- FWI is incorporated for accurate velocity model update, especially in shallow region where velocity tomography loses capability
- Cost function is established on phase or cross-correlation to mitigate amplitude overfitting issue
- Effective preconditioner for convergence acceleration
- Constrained inversion is employed to enhance inversion stability and robustness
- Advanced regularization techniques for image quality improvement